

Bridging the gap between data and sensor information







Roland Koppe, Ana Macario





moorings

Challenges



 Increasing heterogeneity of instruments, data formats, standards, methods, ...

 Small over large to very large projects, but limited resources

 Scalability of technical solutions, and important of curation and help





Mission

Objectives

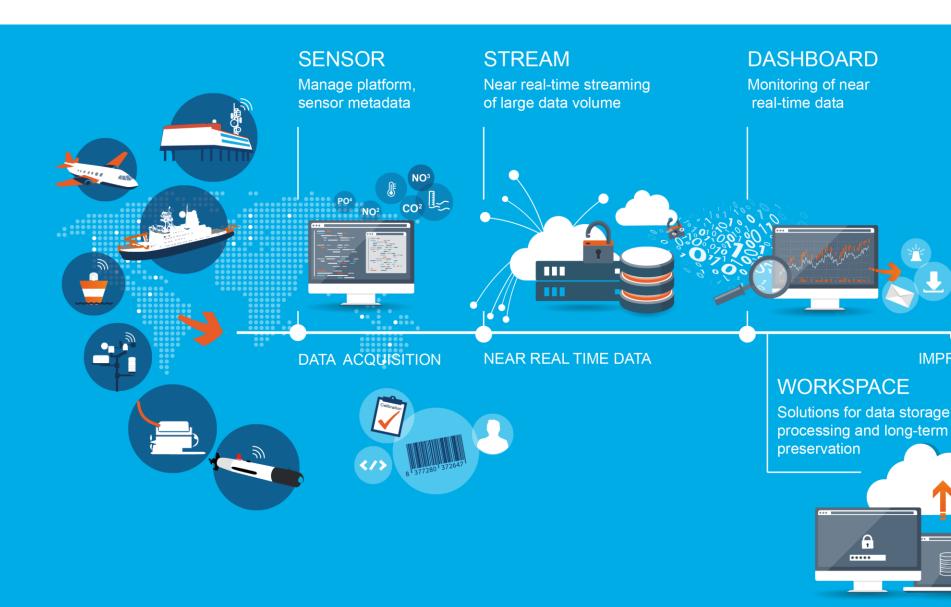


- Generic infrastructure for data flows
- Sustainable and up-to-date services
- Interoperable and support for standards
- Seamless integration of information systems
- User-friendly and simple services



Data Flow Framework – O2A





Data Flow Framework - O2A



DASHBOARD

Monitoring of near real-time data

ANALYSIS

Data viewing and analysis solutions; Map-based visualization services



PORTAL

One-stop-shop framework Interoperability services





REPOSITORIES

Data and data products Publications, presentations, field reports





Subdevices

Might

multibeam sonar, fluorometer, camera, nitrate sensor,...

Description

names, manufacturer, model, description, asset number, ...

Parameters

backscatter, chl a, FDOM, depth, conductivity, dissolved oxygen, temperature, ...

Properties

temperature,

dimension, ...

min / max

weight,

Contact

data scientists, editors, owner, engineer in charge, principal investigator, ...

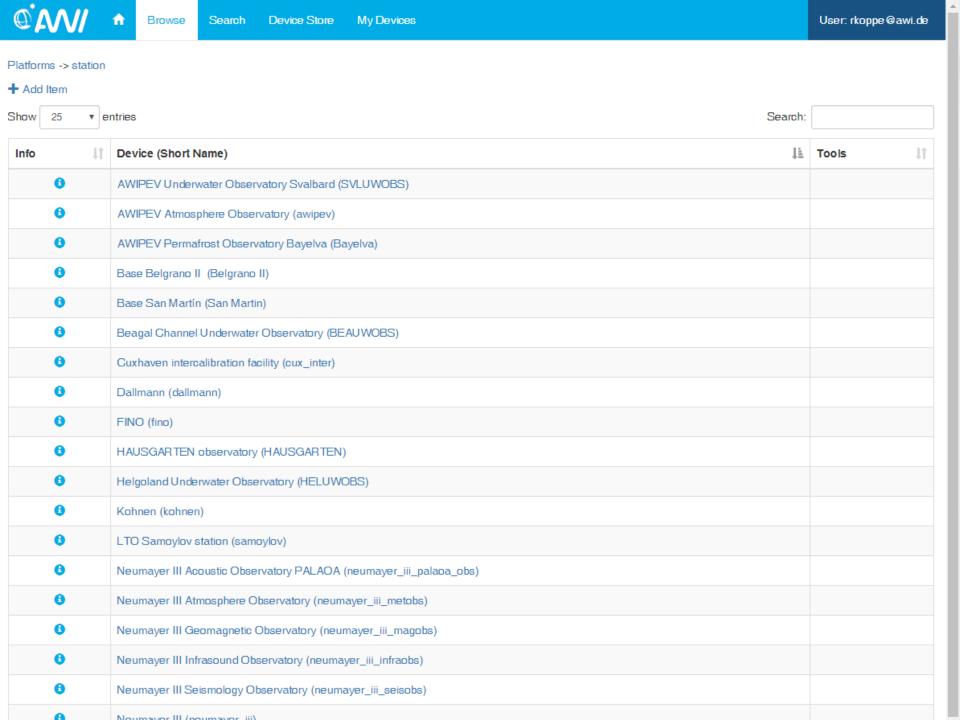
Resources

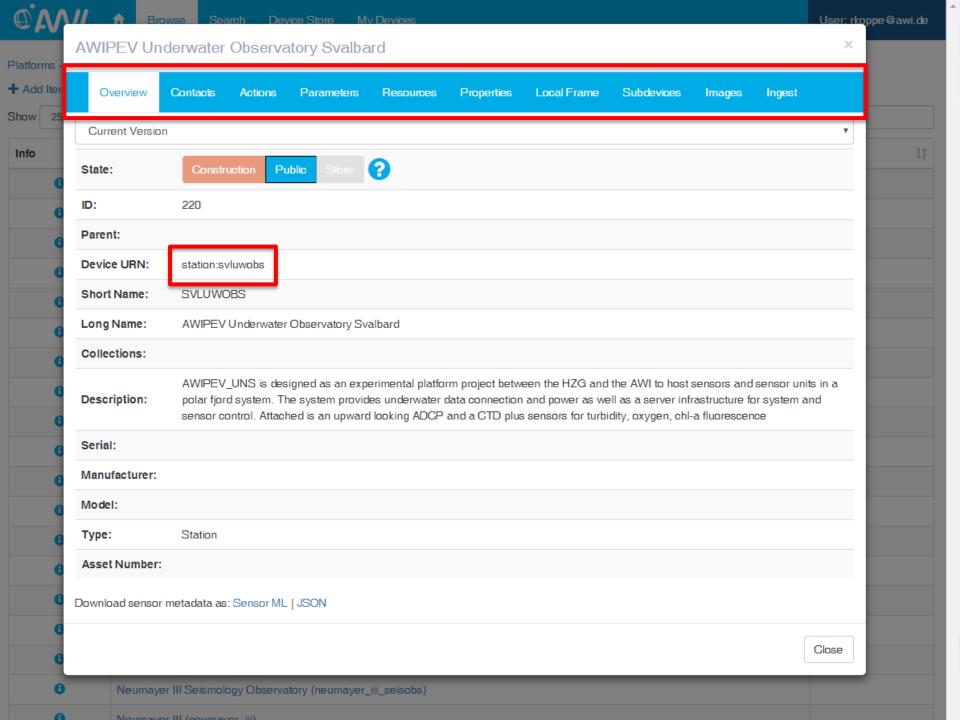
factsheet, calibration certificates, manuals, ...

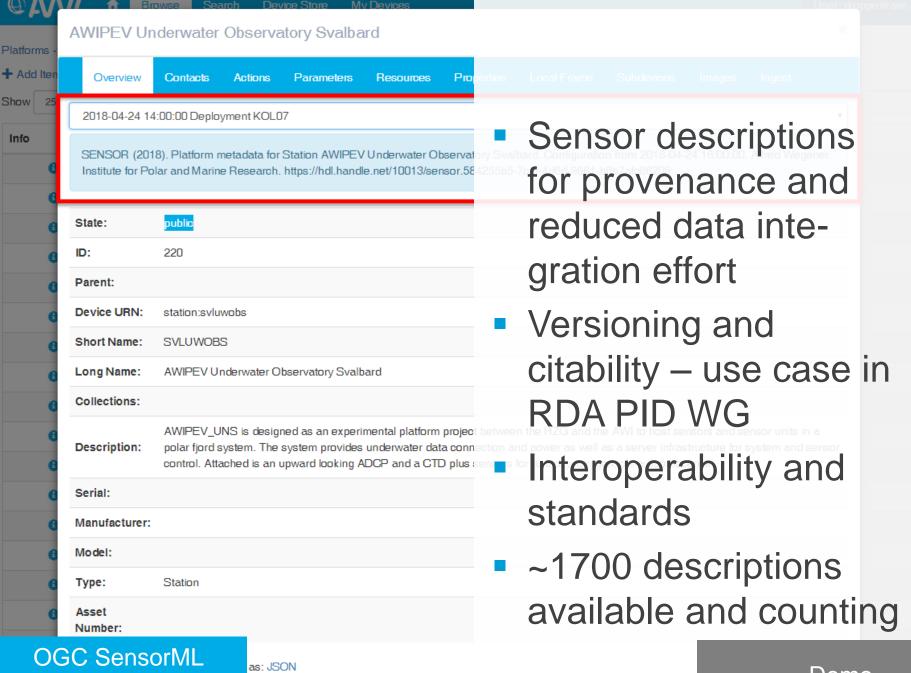
Action

deployment, mount, calibration, failure, information, ...









RDA WGs / IGs

Available sensors

ilter s	ensors: neum							
	Sensor code		Sensor description	Last date	Age	Last value Unit	Platform ID	Sensor ID
	station:neumayer iii:ashtec:latitude		Neumayer III:Ashtec:Latitude	2018-11-02 14:00:00	6 minutes	-70.66725	6	661
)	station:neumayer iii:ashtec:longitude		Neumayer III:Ashtec:Longitude	2018-11-02 14:00:00	6 minutes	-8.27988	6	662
)	station:neumayer iii:gps:latitude	;	Neumayer III:GPS:Latitude	2018-11-02 14:00:00	6 minutes	-70.66683	6	659
)	station:neumayer iii:gps:longitude		Neumayer III:GPS:Longitude	2018-11-02 14:00:00	6 minutes	-8.27967	6	660
	station:neumayer iii:metobs:air_pressure	hPa	Neumayer III:metobs:air_pressure	2018-11-02 14:00:00	6 minutes	981.1 hPa	6	956
	station:neumayer iii:metobs:air_temperature_10m	deg_C	Neumayer III:metobs:air_temperature_10m	2018-11-02 14:00:00	6 minutes	-15.8 deg_C	6	950
	station:neumayer iii:metobs:air_temperature_2m	deg_C	Neumayer III:metobs:air_temperature_2m	2018-11-02 14:00:00	6 minutes	-15.8 deg_C	6	951
)	station:neumayer iii:metobs:visibility	m	Neumayer III:metobs:visibility	2018-11-02 14:00:00	6 minutes	75000.0 m	6	957
)	station:neumayer iii:metobs:wind_direction_10m	deg	Neumayer III:metobs:wind_direction_10m	2018-11-02 14:00:00	6 minutes	282.7 deg	6	952
)	station:neumayer iii:metobs:wind_direction_2m	deg	Neumayer III:metobs:wind_direction_2m	2018-11-02 14:00:00	6 minutes	283.9 deg	6	953
)	station:neumayer iii:metobs:wind_velocity_10m	m/s	Neumayer III:metobs:wind_velocity_10m	2018-11-02 14:00:00	6 minutes	2.8 m/s	6	954
)	station:neumayer iii:metobs:wind_velocity_2m	m/s	Neumayer III:metobs:wind_velocity_2m	2018-11-02 14:00:00	6 minutes	2.4 m/s	6	955
)	station:neumayer iii:weather:		Neumayer III:Weather:				6	874
)	station:neumayer iii:weather:air pressure (43m nn)	hPa	Neumayer III:Weather:Air pressure (43m NN)	2018-02-20 08:16:01	255 days	975.3 hPa	6	42
)	station:neumayer iii:weather:air temperature (2m)	С	Neumayer III:Weather:Air temperature (2m)	2018-02-20 08:16:01	255 days	-8.8 C	6	39
)	station:neumayer iii:weather:relative humidity (2m)	%	Neumayer III:Weather:Relative humidity (2m)	2018-02-20 08:16:01	255 days	89.0 %	6	43
	station:neumayer iii:weather:wind direction (10m)	deg	Neumayer III:Weather:Wind direction (10m)	2018-02-20 08:16:01	255 days	96.0 deg	6	41
)	station:neumayer iii:weather:wind velocity (10m)	m/s	Neumayer III:Weather:Wind velocity (10m)	2018-02-20 08:16:01	255 days	7.5 m/s	6	40

^{18 / 787} sensor(s) are registered for this data service.

Request data

Begin 2018-11-01 End 2018-11-02 Format JSON ▼

Data Web Service ••

[Base URL: /data-xxl/rest]

https://dashboard.awi.de/data-xxl/rest/swagger.json

The data web service allows accessing and storing near real-time and delayed mode data.

- Ingest bound to sensor descriptions
- Generic driver and QC/QA approach
- Monitoring / alarming functionality
- Access to data, quality flags, aggregation statistics, unit conversion, ...

default

GET /data Loads data according to given query parameters.

POST /data Saves data specified in the body

POST /data/bulk Loads data according to the given request in body (see DataRec

DELETE /dataset/{datasetid} Deletes the dataset and the data rows that dep

datasets Returns all existing datasets by provided restrictions, the newest

GET /platforms Returns all known platforms

SOS

that matches the given pattern ('*' allowed as wildcan

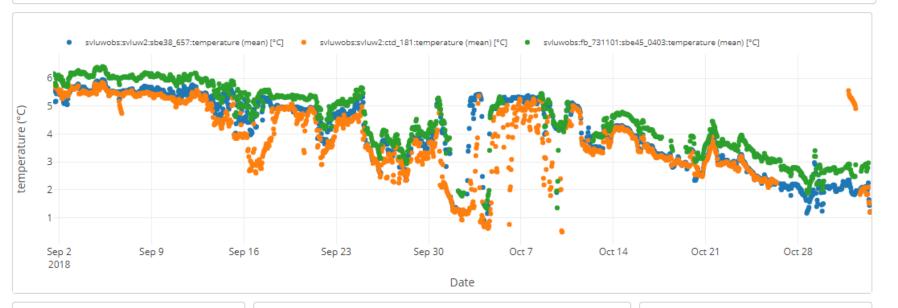




Research Base Water temperatures - NyÅlesund/Svalbard - N 78° 55.200 / E 11° 54.00

PEV (PEV) Focus on specific dates or values by horizontal or vertical left-click dragging a zoom window. Double-click for focus reset.

Click on sensor names in the plots to select/deselect data.



Value: sbe38_657:temperature

The variable "#sbe38_657:temperature" is measured by a temperature probe (SBE38, Company SeaBird) which is mounted at 12 m water depth (+/- tide).

Value: ctd_181:temperature

The variable "#ctd_181:temperature" is measured by a combined conductivity temperature - density probe (CTD90, Company Sea&Sun, Sensor Aanderaa optode) which is profiling every day at 12:25 hours between 11m (+/- tide) and the surface. After this cast, the probe is set to one of the five depth 9m, 7m, 5m, 3m or 1m for 24hours. By this procedure, each depth stratum is sampled for 24 hours once a week.

Value: fb_731101:sbe45_0403:temperatrure

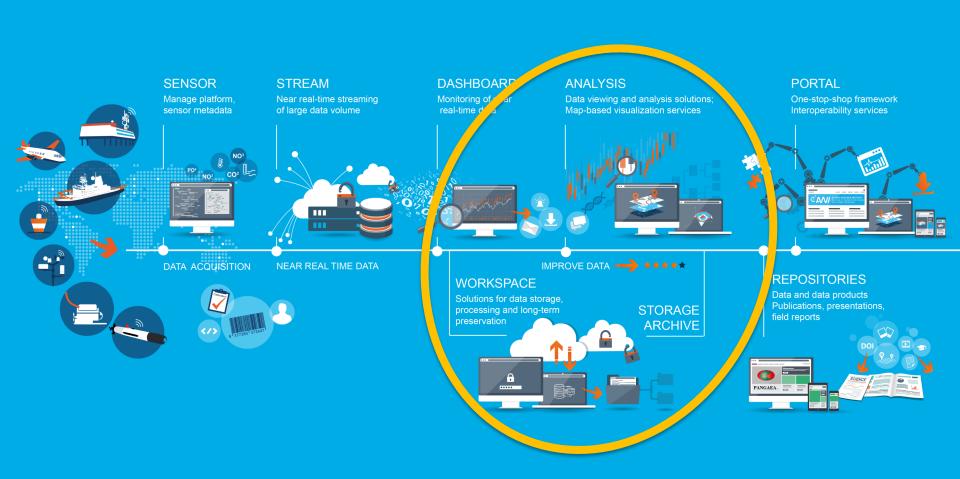
The variable "#fb_731101:sbe45_0403:temperatrure" is measured by a land based FerryBox system (Sensor SBE45, ADM) getting its water from a pumping station in a depth of 11m (+/- tide) close to the base of the underwater observatory.

svluwobs:svluw2:ctd_181:pressure (mean) [dbar]

→ Demo

Data Flow Framework – O2A





Workspace



- Science community workspace for data sharing and data analytics within the Helmholtz Data Federation (HDF)
- State-of-the-art storage, replicated between Bremerhaven and Potsdam
- User-friendly "one-click" compute solutions with virtual machines and containers
- Hadoop big data analysis based on Hortonworks data flow and data platform
- Raster data management and analysis with rasdaman, developments

Elemente

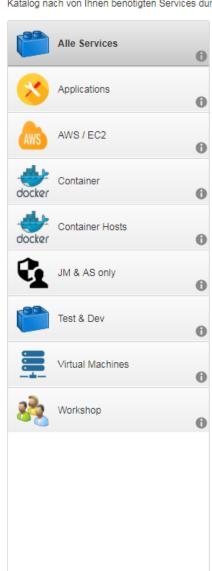
Anforderungen

Posteingang

Business Management

Servicekatalog

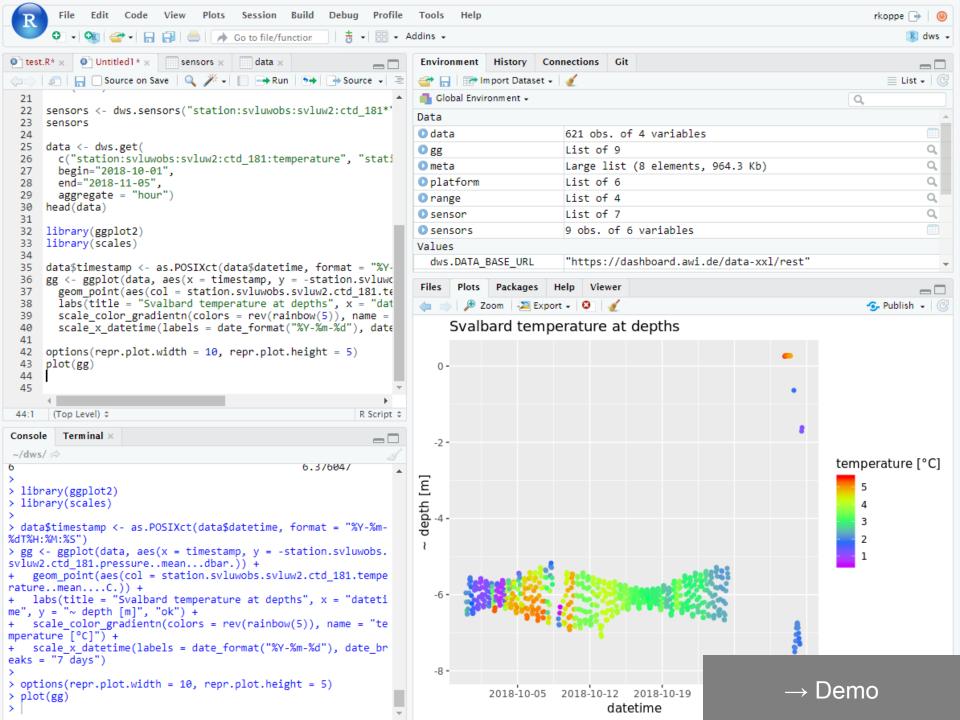
Katalog nach von Ihnen benötigten Services durchsuchen.

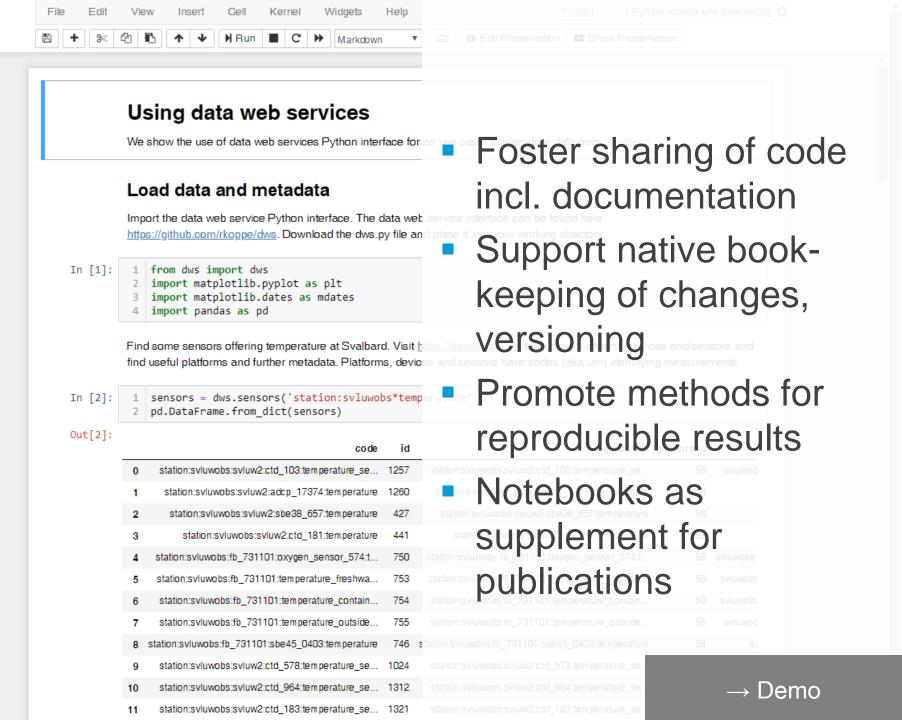




- Cloud management with VMware vRealize
 - Providing tailored short-life containers and virtual machines for scientists
- Including support for hybrid clouds, e.g.
 - Amazon WS

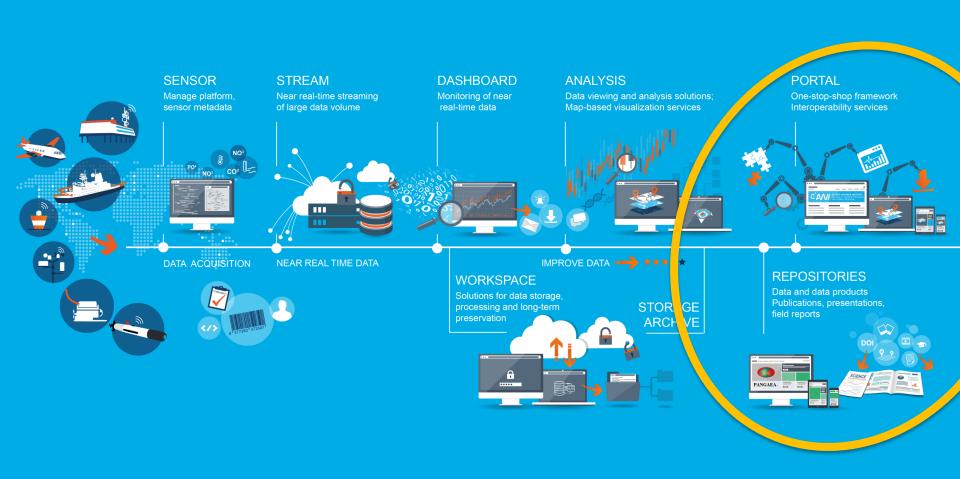




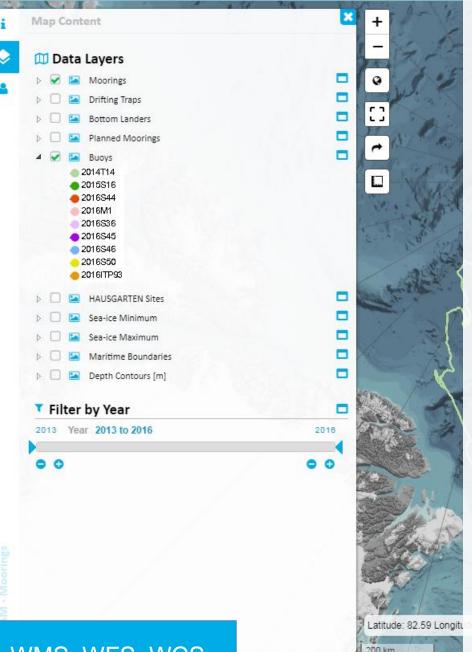


Data Flow Framework





©'AVI



- Map visualization and composition of data products
- Maintaining world base maps in different projections based on RTOPO
- Providing standard products, e.g. satellitebased chlorophyll a and sea ice

PANGAEA.

Data Publisher for Earth & En

2013-07-02 19:58:

SENSOR (2013). F Wegener Institute f

Parent: Device URN:

Short Name:

Long Name:

Collections:

Description:

Manufacturer:

Serial:

Model:

Type:

Asset Number:

Wulff, Thorben; Bauer feind, Eduard; volume Hagans, Inn, Jonas; Lehme wulff, Thorben Q /sical and biogeocl / "PAUL" during a thorben.wulff@awi.de web Page / S94/PA /AWI AUV Polar

Always quote above citation when using below.

RIS Citation BIBTEX Citation Text Citation

Show Map Google Earth

Abstract:

AWI's autonomous underwater vehicle '

Related to:

Wulff, Thorben; Bauerfeind, Eduard; v

Fram Strait as observed with an AUV. In the strain of the

Project(s):

Physical Oceanography @ AWI (AWI_Ph

Coverage:

Median Latitude: 78.753080 * Median Lon bound Latitude: 78.794343 * East-bound

Date/Time Start: 2013-07-02T20:45:38 * D

Minimum DEPTH, water: 1.22 m * Maximu

Q * Latitude Start: 78.714 art: 2013-07-02119:58:00 / hdl:10013/sensor.664525 Deep Sea Research Part I: Oceanographic

 Data archiving and publication (DOI) including curation and harmonization

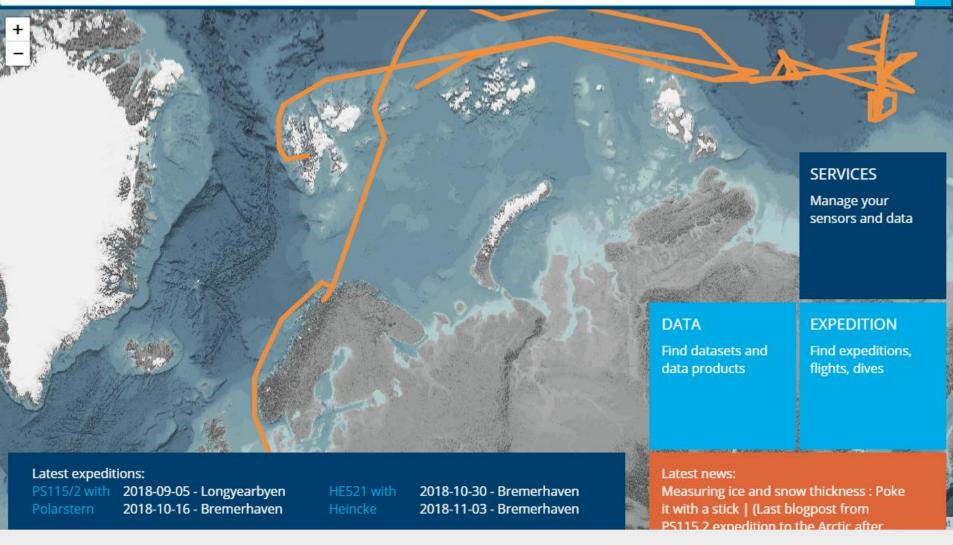
 Linking with articles, platforms, devices, sensors, expeditions, orcid

Semi-automatic data flows when using O2A

 \rightarrow Demo

OAI-PMH, ISO19115, RDA WGs / IGs Search for author, expedition, project, ...





COLLECTIONS

Explore data and products thematically grouped

NEAR REAL TIME DATA

Near real time data is presented in hourly averages and no quality control is applied. Search for author, expedition, project, ...



FRAM

FRontiers in Arctic Marine Monitoring

i





Layers

Dynamic layers

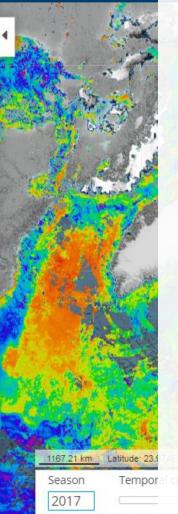
- Sea-ice coverage
- Chlorophyll a

Product layers

- Fram Strait DTM
- ☐ Knipovich Ridge DTM
- Hausgarten major currents
- FESOM sea water temperature
- FESOM sea water salinity

Platform layers

- Platforms
- Buoys



- Portal as central access point to linked and combined data
- Platforms, devices and sensor overviews
- Expeditions
- Data, publications and reports
- Interactive data products



Services

ightarrow Demo





Frontiers in Arctic Marine Monitoring















The expedition's planned duration is 350 days in the ice.



During the expedition, RV Polarstern will be resupplied by 4 icebreakers: Akademik Fedorov (RUS), Admiral Makarov (RUS), Oden (SWE), Xue Long (CHN).





The ice will drift at an average speed of roughly 7 km per day.



The following 17 nations will participate in the expedition:









Around 300 people will work in the background for the expedition in order to realize it.



For 60-90 days the research icebreaker Polarstern will be less than 200 km away from the geographic North Pole.



Throughout the year, a total of 600 experts will be on board, and be exchanged in phases.

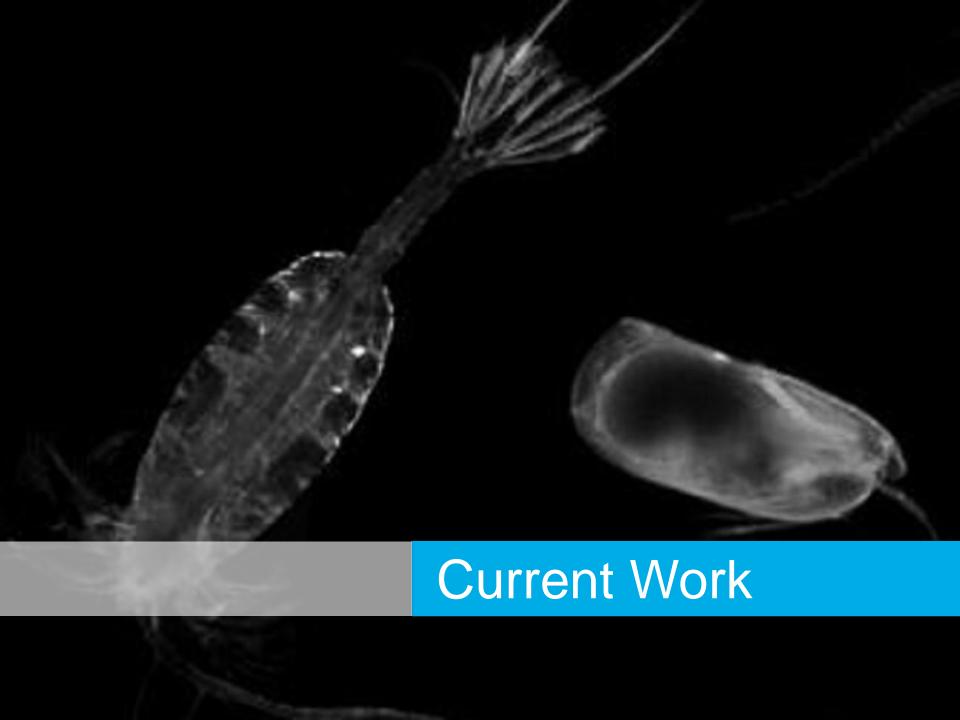


6.000 t of fuel will be required by the research icebreaker Polarstern alone.



RV Polarstern will cover a total of some 2,500 km.





Current Work



- Setup virtual environments for applications like
 3D modelling of the ocean floor
- Develop building blocks for e.g. machine learning methods for images and videos
- User-transparent scaling of computing resources, e.g. with Kubernetes
- Repository of drivers for data ingest and quality procedures incl. best practices
- Computing on GPUs between "standard" virtualization and HPC

• ...





Approach



- Illustrate added value for individuals, give incentives
- Make hands on use as easy as possible
- Provide fast applicable tools and best practices with examples
- Perform regular user sessions to foster community and user-network, beyond projects
- Collect and give feedback



Outlook and Preparations



- Data Management Plans as seamless starting point from project idea, over data ingest and science workspaces to publications
- Legacy systems: refactoring and further integration incl. harmonization of existing vocabularies, e.g. for devices, actions, ...
- New data center on board of Polarstern, remote synchronization of services and data between Arctic and Antarctic over satellites
- Streamline sample management solutions for, e.g. cores and specimen and flow integration



Best Practices Needed



- Continuous measurements, time series
 - how to align tracked sensor information with data
- Combined datasets PIDs for events of distinct instruments
 - how to combine it useful
- Agreements on formats and semantics multipartner and multi-discipline projects
- DMPs simple and actionable
- Integrating data products, prepare it for the community and beyond
- ...



